Names of students in the group:	Nick Vogel Ronald Gayles Alex Certa
Title of project:	Observer-Based Robot Arm Control System
Project Advisor:	Dr. Dempsey
Project Acronym	robotarm
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Project Description:	An observer method has been proposed by George Ellis and is based on classical control theory using a PID control law for tuning. Ellis's method will be the focus of this senior project to determine its advantages and disadvantages for a robot arm system.