Active Suspension System Test Platform Bradley University Department of **Electrical & Computer** Engineering By: Brian Groth & Melanie Hagar

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Outline

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Project Summary

- Drive a platform load with a 115[VDC] motor
- Microcontroller based feedback control system
- User selects starting position and waveform
- Optional analog position input

Previous Work

Linear Actuator

- Power electronics calculations
- Plant Model for Linear Actuator
- System responds with different waveform types
- Bidirectional movement of platform loads

Functional Description

- Responds to a platform load via feedback system
- The mode of operation will be determined by the user via a keypad on the micro-controller.
 - Sinusoidal
 - Step
 - Triangular
 - Ramp
- Flexibility in selecting desired frequency and amplitude of the platform's motion



Inputs & Outputs

System

INPUTS	OUTPUTS
Desired platform motion	Platform movement

EMAC Micropac 535 micro-controller

INPUTS	OUTPUTS
Keypad	Platform movement
Waveform Generator	LCD Display
Feedback Sensor	

Actuator

INPUTS	OUTPUTS
Error signal from controller	Platform movement



Software Subsystem



Hardware Subsystem





Software Flow Chart







Micro Pac 535
115 [VDC] Motor
H-Bridge
Screw Jack

Work Schedule

Fall Semester

- ACTIVEST Project Research
- o 115 [VDC] Motor Modeling

Spring Semester

- Week 1-2 Software Design
- Week 3-4 Software Coding and Platform Construction
- Week 5-7 Software Debugging and Testing
- Week 8-10 System Integration of Hardware and Software Subsystems
- Week 11-13 Research on project expansion and senior presentation preparation

